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Magnetostrictive Level Transmitters Series JLT-6000

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1.0.0 Introduction

1.1.0 Forward

The Jogler JLT-6000 series transmitter represents the latest in magnetostrictive level transmitter technology. Suitable for most liquid level applications, the JLT transmitter provides a very accurate and reliable output for remote level control with zero maintenance. With greater ease of communication and programmability, the JLT series contains the latest state-of-the-art electronics and sensor technology. The JLT series is available in three different configurations; the ILT, LGT and MGT-6000 series. All transmitters are factory calibrated to the specifications required with each order and installation.

The ILT-6000 series transmitter is designed for direct insertion into a storage tank, process vessel or bypass chamber. The ILT can be top or bottom mounted and comes with a patented thermo-well enclosure. As a result, the 316 SS waveguide probe of the transmitter is not exposed directly to the process conditions since it is isolated within the thermowell. Only the thermowell enclosure and level float are exposed to external process conditions. Remote mounted transmitter head locations are available.

The MGT-6000 series transmitter is designed exclusively for magnetic level indicators. The waveguide probe is installed externally on the outside of the magnetic level gage chamber and is not exposed to process conditions. Based on the level gage specifications, top, bottom or remote mounted transmitter head locations are available.

1.2.0 Theory of Operation

Magnetostrictive level transmitters operate in conjunction with a magnetic field that originates from a liquid level float designed for the process media. A two wire waveguide probe of variable length is connected to the transmitter sensor and electronic assembly. The two wire waveguide is housed within a sealed ¼ inch (OD) sensor probe and receives a short current pulse at timed intervals. Disruption of the waveguide is caused by torsion generated by the float's lateral magnetic field at any elevation. This torsion or deflection of the waveguide is detected by the transmitter sensor, which produces a very accurate signal proportionate to the level elevation.



2.0.0 Preparation

2.1.0 Introduction

Jogler JLT series level transmitters are built and designed to exact customer specifications as defined in each model number. Wiring terminations are required and need to follow proper procedures.

2.2.0 Unpacking Freight

Upon receipt, all packages containing Jogler products are to be opened carefully and inspected for freight damages. If damage to the product has occurred due to freight, a claim needs to be made at the point of product receipt and initial inspection within 24 hours. **Jogler does not insure freight or make freight claims on behalf of the owner.** Do not discard the shipping container until all components are accounted and inspected for.

2.3.0 Storage

If the transmitter requires storage for prolonged periods, care must be given to ensure product protection from physical and ambient conditions. Seal the entire device completely from condensation and store it with the shipping materials provided. Do not leave any auxiliary conduit connection open. Recommended storage temperatures are -10 to +130° F.

2.4.0 Electronic Static Discharge

Jogler level transmitters are manufactured from the highest quality electronic components of which can be damaged by static electricity. Care must be taken to eliminate static discharges surrounding the transmitter upon installation. All equipment proximal to the transmitter must be grounded to a secure source. Grounding terminals are provided both inside and outside of the instrument enclosure.

2.5.0 Equipment and Recommended Tools

To attach the JLT series transmitter to an existing piping or vessel connection, the operator will need the following tools:

- Nut drivers for MGT attachment to piping clamps
- Phillips and flat head screwdrivers
- Wrenches for ILT installation
- Digital volt meter to verify and troubleshoot voltage



2.6.0 Temperature Ratings

The maximum ambient temperature rating of the JLT series electronics is -40 to + 160° F. The ambient temperature range of the LED readout is -10 to +160° F. Ambient temperatures above and below that rating may cause the LED readout to malfunction. The transmitter head may require protection from prolonged direct sunlight exposure. Low temperature cryogenic or high temperature insulation blankets should be installed during extreme process operating temperatures.

The maximum process temperature rating of the JLT series transmitter is -40°F to +235° F and applies to the waveguide probe.

2.7.0 Pressure Ratings

The maximum process pressure rating of the JLT series transmitter waveguide probe is 300 PSIG. This rating applies to LGT-6000 series which is a direct insertion model for level gage applications only. The waveguide probe in the ILT-6000 series transmitter is protected by and contained within the thermowell and is therefore not subject to process pressure. The MGT-6000 is an externally mounted transmitter and is not subject to process pressure.

2.8.0 Voltage

The JLT transmitter is designed to operate at 24 Volts DC, nominal. Please ensure that the power supply to the transmitter is the same 24 VDC voltage required. Although the voltage range of the JLT transmitter is +12 to +30 VDC, it is highly recommended that the service voltage is established at a stable and continuous 24 VDC. Higher voltages will damage the transmitter. **Do not connect to AC current since this will damage the transmitter and violate the transmitter warranty.**



3.0.0. Mounting

3.1.0 Introduction

Determine if the installation requires a top, bottom or remote mounted location. Consideration should be given to electrical conduit connections before the transmitter is installed. It is important to verify chemical compatibility with all wetted components.

3.2.0 MGT - Magnetic Level Indicators

- The second bend in the waveguide should be placed at the same elevation of the centerline of the upper or lower process connection, depending upon the preferred transmitter head location.
- The transmitter head contains a special pipe clamp groove for chamber attachment first.
- Insolating **L** brackets are supplied for the waveguide. These maintain an even distance of the waveguide away from the magnetic level gage chamber.
- Corresponding pipe clamps are provided for each **L** bracket position, which should be spaced evenly apart throughout the waveguide.
- Secure the L brackets by tightening each pipe clamp accordingly after the transmitter head is secured.

3.3.0 ILT – Direct Tank Insertion (Waveguide with Thermowell)

- The assembly includes a welded flanged thermo-well and float that is separate from the transmitter head and waveguide.
- Verify if the flanged thermo-well and float assembly matches the connection flange of the tank
 or vessel and is of the specified material. Please note, since the ILT transmitter head, sensor
 and waveguide probe are isolated from the process environment, the material of the
 thermowell assembly can be different.
- Attach the flanged thermo-well and float assembly to the vessel connection flange without the ILT transmitter head and waveguide.
- Slip the transmitter waveguide into the thermo-well after the thermo-well flange is attached to the vessel connection flange.
- Secure the transmitter head, sensor and waveguide by tightening the sensor thread.



4.0.0 Wiring

Connection to the JLT-6000 transmitter requires an electrical conduit connection of $\frac{3}{4}$ inch NPT. The enclosure contains two conduit connection ports (Photograph No. 1). Wiring between the power supply and the JLT-6000 transmitter should be made with 18-22 AWG shielded twisted pair instrument cable.

4.1.0 Connections

Once the electrical conduit is properly connected, the terminal block needs to be accessible for wiring connections. The terminal block is located on the termination board which is attached to the enclosure beneath the sealed transmitter puck. (Photograph No. 2) The transmitter puck plugs into the termination board. The puck will require removal (unplugging) from the termination board in order to gain access to the terminal block. Simply pull the transmitter puck out vertically and carefully. There are three guide pins located on the bottom of the transmitter puck housing. These pins realign the puck perfectly into the termination board upon reinstallation. (Photograph Nos. 3 and 4)

Wiring to the terminal block is as follows:

Terminal Block: POS (+) Positive 24 VDC Red Wire
Terminal Block: NEG (-) Negative Black Wire
Ground Screw: 8-32 NC Inside Enclosure Back Green Wire



Photograph No. 1 Enclosure – Front



Photograph No. 2
Termination Board



Photograph No. 3
Transmitter Puck – Front



Photograph No. 4 Transmitter Puck – Rear

Warning: Electrical connections may induce an explosion hazard. Do not connect or disconnect equipment unless power has been turned off and the installation area has been rendered non-hazardous. Determine the correct polarity before connecting.

The JLT-6000 is designed for Class 1, Division 1, Groups B, C and D hazardous locations. Explosion proof installations could have flammable vapors and liquids present. If disconnecting, instrument covers must remain tight until power is turned off. Make sure that power is off in any junction box if exposed to hazardous atmospheres. Power to the instrument can only be turned on after the installation is complete, instrument covers are tight and secure, the area is non-hazardous and the installation has been checked by the appropriate electrical engineers.



5.0.0 Transmitter Configuration

5.1.0 Introduction

The JLT-6000 transmitter is factory configured to probe length, float density and positioning. The internal parameters that are important to the basic configuration of the transmitter are protected by a factory password and cannot be changed by the end user. The operator is provided with a user password that will be necessary to change some of the basic transmitter settings that are fundamental to transmitter performance.

5.2.0 Operation

Each JLT-6000 can be programmed by the three push buttons (keypad) located on the transmitter head. They are the Up and Down arrow keys and the Select key which are used to navigate the displays and to calibrate the transmitter. The Up and Down arrow keys move forward and backward in the menu structure when in the *scroll* mode and increase and decrease the value displayed when in the *set* mode. The Select key selects the *set* mode when on a menu screen where it is available. The Select key also accepts a value and moves to the next step when in the *set* mode.

The *scroll* or *set* mode is indicated by the lack or presence of the set mode symbol in the upper right hand corner of the screen. Screen scrolling is in ascending order of screen number when the down arrow is depressed and descending order when the up arrow is depressed.

The JLT-6000 has an LCD display that shows two lines of eight characters each. All transmitter menu screens are shown on the LCD display. The display defaults to the scrolling measurement screen that shows the level height (inches or metric), percentage and milliamp outputs. The scrolling default display can be changed to any of the individual three output values at the operator's choice.

5.3.0 Screen Menus

5.3.1 Screen 1: Default Display

Category: Display

Description: Displays one of the following: Level in units, Level in percent, Loop

Output in milliamps, Error Messages. The Default Display is denoted

by the "*" symbol.

Notes: In the event of a transmitter error, the corresponding error message

will be displayed in place of the output. Any of the output types may be displayed or they can be selected to scroll. This selection is made from

Screen No. 5.

5.3.2 Screen 2: Level

Category: Display

Description: Displays the absolute measurement in level units (inches or cm)

Notes: In the event of a transmitter alarm condition, ALARM will be displayed

in place of the level value.



5.3.3 Screen 3: <u>Level %</u>

Category: Display

Description: Displays the value of the primary variable in percent of span. The

range is 0.00% to 100.00%

Notes: In the event of a transmitter alarm condition, ALARM will be displayed

in place of the level value.

5.3.4 Screen 4: Loop

Category: Display

Description: Displays the value of the 4-20 mA current loop in milliamps.

Notes: In the event of a transmitter alarm condition, ALARM will be displayed

in place of the level value

5.3.5 Screen 5: <u>Dft Display</u>

Category: User Setting

Input: Scroll, Level, Level%, Loop (scroll selectable)

Description: Selects the default screen display as either: Scroll, Level, Level % or

Loop

Notes: None

5.3.6 Screen 6: Quick Cal

Category: User Setting

Input: Select 4 mA and 20 mA points based on float position.

Description: Allows the setting of the 0% and 100% points based on the current

float position. The 0% and 100% points may be configured at either end of the probe (i.e. provides for direct OR reverse action). If the 4.00 mA button is pressed, then the current float position is set as the 4 mA elevation. If the 20 mA button is pressed, the current float position is set as the 20 mA elevation. The 0 measured value of the PV is then

equated to the 0% level point by setting the value of the offset.

Notes: This function takes into account the mounting type and also checks for

reverse action settings when computing the offset value.

5.3.7 Screen 7: Units

Category: User Setting

Input: Inches, Centimeters (scroll selectable)
Description: Selects the level units in cm or inches.



5.3.8 Screen 8: <u>4 Ma Set</u>

Category: User Setting

Input: Position of the 4 milliamp (0%) point in inches or cm.

5.3.9 Screen 9: <u>20 Ma Set</u>

Category: User Setting

Input: Position of the 20 milliamp (100%) point in inches or cm.

5.3.10 Screen 10: Offset

Category: User Setting

Input: PV measurement offset in inches or cm.

Description: A positive or negative adjustment to the PV zero reference mark.

5.3.11 Screen 11: Damping

Category: User Setting

Input: Value of the damping time constant in seconds.

Description: Sets value of the damping time constant. Input range is 0-15 seconds

in 0.10 second intervals up to 1.0 second followed by 1.0 second

intervals.

5.3.12 Screen 12: Fault

Category: User Setting

Input: Low, High, Latch (scroll selectable)

Description: Determines the value of the current loop output during a fault

condition. Loop current can be set to 3.60 mA, 22.0 mA or latched to

the value of the current loop just before fault condition occurred.

Notes: If HART communication is detected, the Low value of the current loop

will be set to 3.70 mA instead of 3.60 mA to ensure reliability of

communication.

5.3.13 Screen 13: Poll Adr

Category: User Setting

Input: Integer number in the range 0 - 15.

Description: Sets poll address of the transmitter for use in HART multi-drop mode.



5.3.14 Screen 14: Trim 4

Category: User Setting

Input: Integer number in the range of 0 - 4095. Description: Trims the 4 mA output of the 4 - 20 mA loop.

Notes: Performs a trim of the Digital to Analog Converter (DAC).

5.3.15 Screen 15: <u>Trim 20</u>

Category: User Setting

Input: Integer number in the range of 0 - 4095. Description: Trims the 20 mA output of the 4 - 20 mA loop.

Notes: Performs a trim of the DAC.

5.3.16 Screen 16: Loop Tst

Category: User Setting

Input: Current output in tenths of a mA.

Description: Trims the 20 mA output of the 4 - 20 mA loop.

Notes: Performs a trim of the DAC.

5.3.17 Screen 17: <u>Mnt Pos</u>

Category: User Setting

Input: Tom, Bottom (scroll selectable)

Description: Defines type of mounting as either top or bottom mounted.

5.3.18 Screen 18: DeadZone

Category: Factory Setting

Input: Distance in inches or cm

Description: This is an ignored region (dead zone) measured from the sensing

element. Any signal generated by a magnetic field in this region will not be detected, and will not affect signals in the valid range of the

detection.

5.3.19 Screen 19: Dis Fact

Category: Factory Setting

Input: Yes, No (Scroll Selectable)

Description: This makes the following hidden factory settings visible.

5.3.20 Screen 20: DeviceID

Category: Factory Setting

Input: Yes, No (scroll selectable)

Description: If Yes is selected, the Device ID will be set equal to the Final Assembly

Serial Number and stored in non-volatile memory. This creates a

unique transmitter ID for use in HART communication.



5.3.21 Screen 21: MeasType

Category: Factory Setting (Hidden)
Input: Single, Dual (scroll selectable)

Description: Sets the unit up for a single level measurement or a dual level

measurement.

5.3.22 Screen 22: Probe Ln

Category: User Setting (Hidden)

Input: Length of sensor probe in inches or cm.

Description: Defines the length of the sensor probe. This is the valid range of

detection of a magnetic field along the length of the sensor probe. The length is defined as increasing from the center point of the sensor

element.

Notes: If a signal is detected beyond the set probe length, it will be ignored.

5.3.23 Screen 23: Gradient

Category: Factory Setting (Hidden)

Input: Hundredths of a microsecond per inch.

Description: This is the conversion factor for the time of flight measurement in

microseconds per inch.

5.3.24 Screen 24: Threshld

Category: Factory Setting (Hidden)

Input: Integer number in the range 0 - 255.

Description: Adjusts the threshold voltage level. This is the level of voltage that the

return signal must exceed in order to be detected. The range 0-255 represents a linear range of voltage from 80 mV to 1.55 V for the positive threshold and -80 mV to -1.55 V for the negative threshold.

5.3.25 Screen 25: Polarity

Category: User Setting (Hidden)

Input: Negative, Positive (scroll selectable)

Description: Sets the polarity of the threshold detector.

5.3.26 Screen 26: Senstvty

Category: Factory Setting (Hidden)

Input: Integer from 0-15 representing the sensitivity of the sensing element.

Description: Gain setting for signals received from the sensing element.

Notes: The level of signal gain should be kept at a minimum needed level due

to the amplification of any noise present in the level signal.

5.3.27 Screen 27: Puls Amp

Category: Factory Setting (Hidden)

Input: Integer from 0-255 representing the amplitude of the sensor wire

current pulse.

Description: Gain setting for sensor wire current pulse.



5.3.28 Screen 28: New Pass

Category: User Setting

Input: Integer Value 0-255

Description: Sets the password for menu items in the user setting category.

Notes: Default value is zero.

5.3.29 Screen 29: <u>Lvl Cnts</u>

Category: Display

Description: Displays a count that is directly proportional to the distance between

the sensing element and the detected level signal.

Notes: The count displayed is taken at the output of the damping filter.

Therefore the count will be damped in the same manner at the primary

variable.

5.3.30 Screen 30: <u>Version</u>

Category: Display

Description: Displays the current transmitter type and version.



6.0.0 Troubleshooting

6.1.0 Troubleshooting Matrix

Problem	Symptom(s)	Required Actions	Resolution
_	Blank Display; No Output	Disconnect loop wires and power locally with 24VDC power supply	Check loop wiring for loose connection or loss of power transmission
Does not power up		Measure resistance across fuse "F1" on back of Termination Board (JTT) to determine if blown (must scrape off conformal coating to get a good measurement)	Contact factory for a replacement Termination Board (JTT)
Powers up with blank display	Blank Display; Good output	Check enclosure for evidence of water damage (ex: mineral deposits)	Contact factory for a replacement Electronics Module or Display Board (JTD)
	Alarm output; "No Level Signal"	Hold magnet up to the probe just past the bend	If alarm output, check 2 and 3 pin connectors on back of Termination Board (JTT). If loose, re-secure. If broken, contact factory for a replacement Termination Board (JTT)
Bad Signal		Verify unit is mounted securely to the side of the float chamber.	If unit gives output, move to next Required Action
		If chamber has guide rods, roll the transmitter around the chamber and mount as close to the indicator as possible	If alarm output, move to next Required Action
		Change the setting "DIS FACT" to "YES" to unhide factory settings; Increase SENSITIVITY by 1 unit	If alarm output, contact factory for additional troubleshooting
Bad signal toward end of probe	Alarm output at probe end farthest from the enclosure	Change the setting "DIS FACT" to "YES" to unhide factory settings; Increase Pulse Amplitude "PulsAmp" by 25 units	If it reads further but not all the way to the probe end, repeat the Required Action
Intermittent alarm	Signal reads properly, but intermittently alarms	Change the setting "DIS FACT" to "YES" to unhide factory settings; Increase Pulse Amplitude "PulsAmp" by 25 units	If it improves but still needs adjustment, repeat the Required Action
Slighly bouncy signal	Signal bounces a small amount around true output	Change the setting "DIS FACT" to "YES" to unhide factory settings; Increase Pulse Amplitude "PulsAmp" by 25 units	If no improvement, return Pulse Amplitude "PulsAmp" to original value and move to next Required Action
	around true output	Increase "Threshold" by 25 units	If no improvement, contact factory for additional troubleshooting
Extremely bouncy signal	Signal wildly bounces the entire span or nearly the entire span of the unit	Disconnect loop wires and power locally with 24VDC power supply	If the transmitter operates properly, check loop wires for loose connection or noise from an external source
			If no improvement, contact factory for additional troubleshooting

(NOTE: Password is 5)



6.2.0 Recalibration

To change the transmitter span or to reset the 4 and 20mA setpoint, first get the float at the desired 4mA location. Go to the setting called "Quick Cal" and hit the enter button. An & symbol at the top-right of the LCD shows that the setting is available to change. Hit the button under the 4 to set the 4mA point. (This sets the value in the setting call "4mA Set") Now move the float to the desired 20mA location and Quick Cal the 20. Verify the output has been adjusted and properly tracks float movement.

6.3.0 Swap a mount position (Top to Bottom / Bottom to Top)

If the transmitter has been mounted upside down or swapped in the field, 3 settings need to be changed: Mount Position, 4mA Set, 20mA Set.

Go to the setting "Mnt Pos". Change this setting from Top to Bottom or Bottom to Top depending on where the electronics are located. Now go to 4mA Set and 20mA set and swap these numbers. Verify the output in mA and In/cm has been correctly swapped. If the display is upside down remove the electronics module, unscrew the termination board, turn to the desired orientation and reassemble.



7.0.0 References

7.1.0 Warranty

Jogler electronic level controls are warranted from defects, both parts and complete assemblies, for 365 days from the date of factory direct shipment to the operator / owner. The warranty does not commence at the time of process system start up.

In the event of product return during the warranty period, all components are first inspected for abnormal physical and electronic defects. If the subject item is determined covered under the standard warranty, Jogler will replace or repair the device at no cost to the owner.

Jogler is not liable for warranty claims on any level control that has been misapplied, mishandled, or installed improperly based on the parameters outlined in this manual. This also applies to products damaged by freight without claims filed in a timely manner.

7.2.0 Quality Control

Jogler's quality control program is based on ISO-9001 domestic and international standards. All JLT series transmitters and component parts are fabricated and in compliance with international and domestic ISO guidelines. Jogler is committed to full customer satisfaction both in products and in service.

7.3.0 Model Numbers

<u>Model</u>	<u>Description</u>
ILT-6000	Direct tank insertion within thermowell, waveguide probe is non-intrusive.
MGT-6000	Magnetic level gage, externally mounted, waveguide probe is non-intrusive.



7.4.0 Specifications

7.4.1 Performance

Accuracy +/- 0.015 inches
Repeatability 0.001% of full span
Linearity 0.020% of full span
Rate of Change (Max) 6 inches per second
Refresh Rate 10 times per second

Initiation 0.00 seconds

Damping 0.00 to 1.00 @ 0.01 second increments 1.00 to 25.0 @ 1.00 second increments

Unusable Region 1.00 inch (at end of probe)
Dead Zone 0.00 inch (user specify)

Humidity 0.00 - 99.0% (non-condensing)

7.4.2 <u>Electrical</u>

Input 12-30 VDC (24 VDC Nominal)

Output 4-20 mA

Resistance 600 Ohms (max) @ 24 VDC

Power Consumption 0.66 Watt (30 VDC x 0.022 ohms = 0.66 W)

Error Signal 3.60 or 22 mA

Interface 3 button keypad, HART, or PACT software

Display 2 line 8 character LCD

Values Inches or centimeters, percent of level, mA

7.4.3 Ratings

Process Pressure 300 PSIG @ 100° F LGT only
Ambient Temperature -40° to +160° F (-40° to +70° C) Electronics
-10° to +160° F (-40° to +70° C) LCD Readout

Process Temperature

Standard -40° to +235° F (-40° to +114° C) All Models HT Version -40° to +400° F (-40° to +214° C) ILT & MGT

7.4.4 Enclosure

Type Single Compartment

Material Cast Aluminum (optional 316 SS)

Finish Polyester Powder Coat

Rating FM (Canada & US), Type Nema 4X

7.4.5 Sensor

Material 316 SS, (optional CPVC, Hastelloy, Alloy 20)

Length 6.00 to 300 inches



7.5.0 Industry Approvals

<u>Agency</u>	Model	Protection	Area Classification
FM (Canada & US)	ILT-6000 MGT-6000	Intrinsically Safe	Class I, Division 1: Groups A, B, C, & D Class II, Division 1: Groups E, F, G Class III, Nema Type 4X
	ILT-6000 MGT-6000	Explosion Proof	Class I, Division 1: Groups B, C, & D Class II, Division 1: Groups E, F, G Nema Type 4X